## ML9207-xx

$5 \times 7$ Dot Character $\times 16$-Digit Display Controller/Driver with Character RAM

## GENERAL DESCRIPTION

The ML9207-xx is a dot matrix vacuum fluorescent display tube controller driver IC which displays characters, numerics and symbols.
Dot matrix vacuum fluorescent display tube drive signals are generated by serial data sent from a micro-controller. A display system is easily realized by internal ROM and RAM for character display.
The ML9207-xx has low power consumption since it is made by CMOS process technology.
-01 is available as a general-purpose code.
Custom codes are provided on customer's request.

## FEATURES

- Logic power supply ( $\mathrm{V}_{\mathrm{DD}}$ )
: $3.3 \mathrm{~V} \pm 10 \%$ or $5.0 \mathrm{~V} \pm 10 \%$
- Fluorescent display tube drive power supply $\left(\mathrm{V}_{\mathrm{DISP}}\right): 3.3 \mathrm{~V} \pm 10 \%$ or $5.0 \mathrm{~V} \pm 10 \%$
- Fluorescent display tube drive power supply $\left(\mathrm{V}_{\mathrm{FL}}\right)$ : -20 to -60 V
- VFD driver output current (VFD driver output can be connected directly to the fluorescent display tube. No pull-down resistor is required.)
- Segment driver (SEG1 to SEG35)

| $:-5.0 \mathrm{~mA}$ | $\left(\mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}\right)$ |
| :--- | :--- |
| $:-10.0 \mathrm{~mA}$ | $\left(\mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}\right)$ |
| $:-50.0 \mathrm{~mA}$ | $\left(\mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}\right)$ |

- Grid driver (COM1 to COM24)

$$
:-50.0 \mathrm{~mA} \quad\left(\mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}\right)
$$

- General output port output current
$: \pm 1.0 \mathrm{~mA}\left(\mathrm{~V}_{\mathrm{DD}}=3.3 \mathrm{~V} \pm 10 \%\right)$

$$
\pm 2.0 \mathrm{~mA}\left(\mathrm{~V}_{\mathrm{DD}}=5.0 \mathrm{~V} \pm 10 \%\right)
$$

- Content of display
- CGROM $5 \times 7$ dots $: 240$ types (character data)
- CGRAM $5 \times 7$ dots : 16 types (character data)
- ADRAM 24 (display digit) $\times 4$ bits (symbol data)
- DCRAM 24 (display digit) $\times 8$ bits (register for character data display)
- General output port 4 bits (static operation)
- Display control function
- Display digit :9 to 24 digits
- Display duty (brightness adjustment) : 0/1024 to 960/1024
- All lights ON/OFF
- 4 interfaces with microcontroller
: DA, $\overline{\mathrm{CS}}, \overline{\mathrm{CP}}, \overline{\mathrm{RESET}}$
- 1-byte instruction execution (excluding data write to RAM and Display duty set)
- Built-in oscillation circuit
- Crystal oscillation or ceramic oscillation
- Package options:

80-pin QFP package (QFP80-P-1414-0.65-K) (Product name : ML9207-xxGP)
80-pin QFP package (QFP80-P-1420-0.80-BK) (Product name : ML9207-xxGA) xx indicates the code number.

## BLOCK DIAGRAM



## SCHEMATIC DIAGRAM OF DRIVER OUTPUT CIRCUIT



## PIN CONFIGURATION (TOP VIEW)



NC: No connection

80-Pin Plastic QFP
(QFP80-P-1414-0.65-K)


## PIN DESCRIPTION

| Pin |  | Symbol | Type | Connects to | Description |
| :---: | :---: | :---: | :---: | :---: | :---: |
| QFP-1 * | QFP-2* |  |  |  |  |
| 3 to 37 | 5 to 39 | SEG1 to 35 | 0 | Fluorescent tube anode electrode | Fluorescent display tube anode electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. $\mathrm{I}_{\mathrm{OH}}>-5.0 \mathrm{~mA}$ |
| 39 to 62 | 41 to 64 | COM1 to 24 | 0 | Fluorescent tube grid electrode | Fluorescent display tube grid electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. $\mathrm{I}_{\mathrm{OH}}>-50.0 \mathrm{~mA}$ |
| $\begin{gathered} 1,2,79 \\ 80 \end{gathered}$ | 1 to 4 | AD1 to AD4 | 0 | Fluorescent tube anode electrode | Fluorescent display tube anode electrode drive output. Directly connected to fluorescent display tube and a pull-down resistor is not necessary. $\mathrm{I}_{\mathrm{OH}}>-10.0 \mathrm{~mA}$ |
| 72 to 75 | 74 to 77 | P1 to P4 | 0 | LED anode electrode | General port output. Output of these pins in static operation, so these pins can drive the LED. $\mathrm{I}_{\mathrm{OH}}>-2.0 \mathrm{~mA}$ |
| 71 | 73 | $V_{D D}$ |  |  | $\mathrm{V}_{\mathrm{DD}}-\mathrm{GND}$ are power supplies for internal logic. |
| 38, 78 | 40, 80 | $\mathrm{V}_{\text {DISP1 to } 2}$ |  | er sup | $\mathrm{V}_{\text {DISP }}-\mathrm{V}_{\text {FL }}$ are power supplies for driving |
| 64 | 66 | GND |  |  | fluorescent tubes. Use the same power supply |
| 63, 76 | 65, 78 | $\mathrm{V}_{\mathrm{FL} 1 \text { to } 2}$ |  |  | for $\mathrm{V}_{\text {DD }}$ and $\mathrm{V}_{\text {DISP }}$. |
| 70 | 72 | DA | 1 | Microcontroller | Serial data input (positive logic). Input from LSB. |
| 69 | 71 | $\overline{\mathrm{CP}}$ | 1 | Microcontroller | Shift clock input. Serial data is shifted on the rising edge of $\overline{\mathrm{CP}}$. |
| 68 | 70 | $\overline{C S}$ | 1 | Microcontroller | Chip select input. Serial data transfer is disabled when $\overline{\mathrm{CS}}$ pin is " H " level. |
| 67 | 69 | $\overline{\text { RESET }}$ | 1 | Microcontroller | Reset input. <br> "Low" initializes all the functions. Initial status is as follows. <br> - Address of each RAM .... address " 00 " H <br> - Data of each RAM .......... Content is undefined <br> - Display digit $\qquad$ .24 digits <br> - Brightness adjusment $\qquad$ 0/1024 <br> - All lights ON or OFF $\qquad$ OFF mode <br> - All outputs $\qquad$ "Low" level |
| 65 | 67 | OSC0 | 1 | Crystal or | Pins for self-oscillation. <br> (Do not apply external clocks to these pins.) Connect these pins to the crystal and capacitors or to the ceramic resonator and capacitors. |
| 66 | 68 | OSC1 | 0 |  | The target oscillation frequency is 4.0 MHz . <br> (Note that the device includes the feed back resistor of $1 \mathrm{M} \Omega$ ) <br> See Application Circuit. |
| $\begin{aligned} & \text { QFP1: } \\ & \text { QFP2 : } \end{aligned}$ | QFP80-P-1 | 14-0.65-K |  |  |  |

## ABSOLUTE MAXIMUM RATINGS

| Parameter | Symbol |  | Condition | Rating | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage (1) | $V_{D D}$ |  | *1 | -0.3 to +6.5 | V |
|  | $\mathrm{V}_{\text {DISP }}$ |  | *1 | -0.3 to +6.5 | V |
| Supply Voltage (2) | $\mathrm{V}_{\mathrm{FL}}$ |  | - | -80 to $\mathrm{V}_{\text {DISP }}+0.3$ | V |
| Input Voltage | $\mathrm{V}_{\text {IN }}$ |  | - | -0.3 to $\mathrm{V}_{\mathrm{DD}}+0.3$ | V |
| Power Dissipation | $\mathrm{P}_{\mathrm{D}}$ | $\mathrm{Ta} \geq 25^{\circ} \mathrm{C}$ | QFP80-P-1414-0.65-K | 637 | mW |
|  |  |  | QFP80-P-1420-0.80-BK | 764 |  |
| Storage Temperature | $\mathrm{T}_{\text {STG }}$ |  | - | -55 to +150 | ${ }^{\circ} \mathrm{C}$ |
| Output Current | $\mathrm{I}_{01}$ |  | OM1 to COM24 | -60 to 0.0 | mA |
|  | $\mathrm{I}_{02}$ |  | AD1 to AD4 | -20 to 0.0 |  |
|  | $\mathrm{I}_{03}$ |  | EG1 to SEG35 | -10 to 0.0 |  |
|  | $\mathrm{I}_{04}$ |  | P1 to P4 | -4.0 to +4.0 |  |

*1: Use the same power supply for $\mathrm{V}_{\mathrm{DD}}$ and $\mathrm{V}_{\mathrm{DISP}}$.

## RECOMMENDED OPERATING CONDITIONS

When the power supply voltage is 5 V (typ.)

| Parameter | Symbol | Condition | Min. | Typ. | Max. | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage (1) | $\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{DISP}}$ | - | 4.5 | 5.0 | 5.5 | V |
| Supply Voltage (2) | $\mathrm{V}_{\mathrm{FL}}$ | - | -60 | - | -20 | V |
| High Level Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | All input pins excluding OSC0 pin | $0.7 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| Low Level Input Voltage | $\mathrm{V}_{\mathrm{IL}}$ | All input pins excluding OSC0 pin | - | - | $0.3 \mathrm{~V}_{\mathrm{DD}}$ | V |
| $\overline{\mathrm{CP}}$ Frequency | - | - | - | 2.0 | MHz |  |
| Oscillation Frequency | $\mathrm{f}_{\mathrm{CSC}}$ | - | Self-oscillation | 3.5 | 4.0 | 4.5 |
| Frame Frequency | $\mathrm{f}_{\mathrm{FR}}$ | DIGIT $=1$ to 24, Self-oscillation | 142 | 163 | 183 | Hz |
| Operating Temperature | $\mathrm{T}_{\mathrm{OP}}$ | - | -40 | - | +85 | ${ }^{\circ} \mathrm{C}$ |

When the power supply voltage is 3.3 V (typ.)

| Parameter | Symbol | Condition | Min. | Typ . | Max. | Unit |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| Supply Voltage (1) | $\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{DISP}}$ | - | 3.0 | 3.3 | 3.6 | V |
| Supply Voltage (2) | $\mathrm{V}_{\mathrm{FL}}$ | - | -60 | - | -20 | V |
| High Level Input Voltage | $\mathrm{V}_{\mathrm{IH}}$ | All input pins excluding OSC0 pin | $0.8 \mathrm{~V}_{\mathrm{DD}}$ | - | - | V |
| Low Level Input Voltage | $\mathrm{V}_{\mathrm{IL}}$ | All input pins excluding OSC0 pin | - | - | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | V |
| $\overline{\mathrm{CP}}$ Frequency | - | - | - | 2.0 | MHz |  |
| Oscillation Frequency | $\mathrm{f}_{\mathrm{CSC}}$ | - | Self-oscillation | 3.5 | 4.0 | 4.5 |
| Frame Frequency | $\mathrm{f}_{\mathrm{FR}}$ | DIGIT $=1$ to 24, Self-oscillation | 142 | 163 | 183 | Hzz |
| Operating Temperature | $\mathrm{T}_{\mathrm{OP}}$ | - | -40 | - | +85 | ${ }^{\circ} \mathrm{C}$ |

## ELECTRICAL CHARACTERISTICS

## DC Characteristics-1

$\left(\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\text {DISP }}=5.0 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}, \mathrm{Ta}=-40\right.$ to $+85^{\circ} \mathrm{C}$, unless otherwise specified)

| Parameter | Symbol | Applied pin |  | Condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| High Level Input Voltage | $\mathrm{V}_{\text {IH }}$ | $\begin{gathered} \overline{\mathrm{CS}, \overline{\mathrm{CP}}, \mathrm{DA},} \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | - | $0.7 \mathrm{~V}_{\mathrm{DD}}$ | - | V |
| Low Level Input Voltage | $\mathrm{V}_{\text {IL }}$ | $\frac{\overline{\mathrm{CS}}, \overline{\mathrm{CP}}, \mathrm{DA},}{\overline{\mathrm{RESET}}}$ |  | - | - | $0.3 \mathrm{~V}_{\mathrm{DD}}$ | V |
| High Level Input Current | $\mathrm{I}_{\mathrm{H}}$ | $\begin{gathered} \overline{\mathrm{CS}}, \overline{\mathrm{CP}, \mathrm{DA}}, \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | $\mathrm{V}_{I H}=\mathrm{V}_{\mathrm{DD}}$ | -1.0 | +1.0 | $\mu \mathrm{A}$ |
| Low Level Input Current | $\mathrm{I}_{\text {L }}$ | $\begin{gathered} \overline{\mathrm{CS}}, \overline{\mathrm{CP}, \mathrm{DA}}, \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | $\mathrm{V}_{\text {IL }}=0.0 \mathrm{~V}$ | -1.0 | +1.0 | $\mu \mathrm{A}$ |
| High Level Output Voltage | $\mathrm{V}_{\mathrm{OH} 1}$ | COM1 to 24 | $\mathrm{I}_{\mathrm{OH} 1}=-50.0 \mathrm{~mA}$ |  | $\begin{aligned} & \mathrm{V}_{\text {DISP }} \\ & -20 \end{aligned}$ | - | V |
|  | $\mathrm{V}_{\mathrm{OH} 2}$ | AD1 to AD4 | $\mathrm{I}_{\mathrm{OH} 2}=-10.0 \mathrm{~mA}$ |  | $\begin{aligned} & \hline \mathrm{V}_{\mathrm{DISP}} \\ & -1.5 \end{aligned}$ | - | V |
|  | $\mathrm{V}_{\text {OH3 }}$ | SEG1 to 35 | $\mathrm{I}_{\text {ОН }}=-5.0 \mathrm{~mA}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{DISP}} \\ -1.5 \end{gathered}$ | - | V |
|  | $\mathrm{V}_{\text {OH4 }}$ | P1 to P4 | $\mathrm{I}_{\mathrm{OH} 4}=-2.0 \mathrm{~mA}$ |  | $\begin{array}{r} \mathrm{V}_{\mathrm{DD}} \\ -1.0 \end{array}$ | - | V |
| Low Level Output Voltage | $\mathrm{V}_{\text {OL1 }}$ | COM1 to 24 AD1 to AD4 SEG1 to 35 |  | - | - | $\mathrm{V}_{\mathrm{FL}}+1.0$ | V |
|  | $\mathrm{V}_{\mathrm{OL} 2}$ | P1 to P4 | $\mathrm{I}_{\mathrm{OL} 1}=2 \mathrm{~mA}$ |  | - | 1.0 | V |
| Supply Current | $\mathrm{I}_{\mathrm{DD} 1}$ | $\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\text {DISP }}$ | $\mathrm{f}_{\mathrm{osc}}=$ <br> 4 MHz , <br> no load | $\begin{aligned} & \text { Duty }=960 / 1024 \\ & \text { Digit }=1 \text { to } 24 \\ & \text { All output lights } \\ & \text { ON } \end{aligned}$ | - | 6 | mA |
|  | $\mathrm{I}_{\mathrm{DD} 2}$ |  |  | $\begin{aligned} & \text { Duty }=0 / 1024 \\ & \text { Digit }=1 \text { to } 9 \\ & \text { All output lights } \\ & \text { OFF } \end{aligned}$ | - | 5 | mA |

## DC Characteristics-2

| $\left(\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\text {DISP }}=3.3 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}, \mathrm{Ta}=-40\right.$ to $+85^{\circ} \mathrm{C}$, unless otherwise specified |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Parameter | Symbol | Applied pin |  | Condition | Min. | Max. | Unit |
| High Level Input Voltage | $\mathrm{V}_{\text {IH }}$ | $\begin{gathered} \overline{\mathrm{CS}, \overline{\mathrm{CP}}, \mathrm{DA},} \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | - | 0.8 V D | - | V |
| Low Level Input Voltage | $\mathrm{V}_{\text {IL }}$ | $\begin{gathered} \overline{\mathrm{CS}}, \overline{\mathrm{CP}}, \mathrm{DA}, \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | - | - | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | V |
| High Level Input Current | $\mathrm{I}_{\mathrm{H}}$ | $\frac{\overline{\mathrm{CS}}, \overline{\mathrm{CP}}, \mathrm{DA},}{\overline{\mathrm{RESET}}}$ |  | $\mathrm{V}_{\mathrm{IH}}=\mathrm{V}_{\mathrm{DD}}$ | -1.0 | +1.0 | $\mu \mathrm{A}$ |
| Low Level Input Current | 1 IL | $\begin{gathered} \overline{\mathrm{CS}}, \overline{\mathrm{CP}, \mathrm{DA}}, \\ \overline{\mathrm{RESET}} \end{gathered}$ |  | $\mathrm{V}_{\text {IL }}=0.0 \mathrm{~V}$ | -1.0 | +1.0 | $\mu \mathrm{A}$ |
| High Level Output Voltage | $\mathrm{V}_{\mathrm{OH} 1}$ | COM1 to 24 | $\mathrm{I}_{\mathrm{OH} 1}=-50.0 \mathrm{~mA}$ |  | $\begin{aligned} & \mathrm{V}_{\text {DISP }} \\ & -2.0 \end{aligned}$ | - | V |
|  | $\mathrm{V}_{\mathrm{OH} 2}$ | AD1 to AD4 | $\mathrm{I}_{\mathrm{OH} 2}=-10.0 \mathrm{~mA}$ |  | $\begin{gathered} \hline \mathrm{V}_{\mathrm{DISP}} \\ -1.5 \end{gathered}$ | - | V |
|  | $\mathrm{V}_{\text {OH3 }}$ | SEG1 to 35 | $\mathrm{I}_{\text {онз }}=-5.0 \mathrm{~mA}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{DISP}} \\ -1.5 \end{gathered}$ | - | V |
|  | $\mathrm{V}_{\mathrm{OH} 4}$ | P1 to P4 | $\mathrm{I}_{\mathrm{OH} 4}=-1.0 \mathrm{~mA}$ |  | $\begin{gathered} \mathrm{V}_{\mathrm{DD}} \\ -1.0 \end{gathered}$ | - | V |
| Low Level Output Voltage | $\mathrm{V}_{\text {OL1 }}$ | COM1 to 24 AD1 to AD4 SEG1 to 35 |  | - | - | $\mathrm{V}_{\mathrm{FL}}+1.0$ | V |
|  | $\mathrm{V}_{\mathrm{OL} 2}$ | P1 to P4 | $\mathrm{I}_{\mathrm{OL} 1}=1 \mathrm{~mA}$ |  | - | 1.0 | V |
| Supply Current | $\mathrm{I}_{\mathrm{DD} 1}$ | $\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{DISP}}$ | $\mathrm{f}_{\mathrm{osc}}=$ <br> 4 MHz , <br> no load | $\begin{aligned} & \text { Duty }=960 / 1024 \\ & \text { Digit }=1 \text { to } 24 \\ & \text { All output lights } \end{aligned}$ ON | - | 5 | mA |
|  | $\mathrm{I}_{\mathrm{D} 2}$ |  |  | $\begin{aligned} & \text { Duty }=0 / 1024 \\ & \text { Digit }=1 \text { to } 9 \\ & \text { All output lights } \\ & \text { OFF } \end{aligned}$ | - | 4 | mA |

## AC Characteristics-1

$\left(\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{DISP}}=5.0 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}, \mathrm{Ta}=-40\right.$ to $+85^{\circ} \mathrm{C}$, unless otherwise specified)

| Parameter | Symbol |  | Condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{\mathrm{CP}}$ Frequency | $\mathrm{f}_{\mathrm{c}}$ |  | - | - | 2.0 | MHz |
| $\overline{\overline{C P}}$ Pulse Width | $\mathrm{t}_{\mathrm{cw}}$ |  | - | 250 | - | ns |
| DA Setup Time | $t_{\text {DS }}$ |  | - | 250 | - | ns |
| DA Hold Time | $\mathrm{t}_{\mathrm{DH}}$ |  | - | 250 | - | ns |
| $\overline{\mathrm{CS}}$ Setup Time | $\mathrm{t}_{\text {css }}$ |  | - | 250 | - | ns |
| $\overline{\text { CS }}$ Hold Time | $\mathrm{t}_{\text {cSH }}$ |  | If-oscillation | 16 | - | $\mu \mathrm{S}$ |
| $\overline{\text { CS }}$ Wait Time | $\mathrm{t}_{\text {csw }}$ |  | - | 250 | - | ns |
| Data Processing Time | $\mathrm{t}_{\text {DOFF }}$ |  | lf-oscillation | 8 | - | $\mu \mathrm{s}$ |
| RESET Pulse Width | $\mathrm{t}_{\text {WRES }}$ | When $\bar{R}$ <br> microco | T signal is input from oller, etc. externally | 250 | - | ns |
| $\overline{\text { RESET Time }}$ | $\mathrm{t}_{\text {RSON }}$ |  | - | $\mathrm{t}_{\text {OsCon }}$ | - | ns |
| DA Wait Time | $\mathrm{t}_{\text {RSOFF }}$ |  | - | 250 | - | ns |
| All Output Slew Rate | $\mathrm{t}_{\mathrm{R}}$ | $\mathrm{C}_{1}=100 \mathrm{pF}$ | $\mathrm{t}_{\mathrm{R}}=20 \%$ to $80 \%$ | - | 2.0 | $\mu \mathrm{s}$ |
|  | $\mathrm{t}_{\mathrm{F}}$ |  | $\mathrm{t}_{\mathrm{F}}=80 \%$ to $20 \%$ | - | 2.0 | $\mu \mathrm{s}$ |
| OSC Duty Ratio | $\mathrm{du}_{\mathrm{osc}}$ |  | - | 40 | 60 | \% |
| Oscillation Start-up time | $\mathrm{t}_{\text {oscon }}$ |  | - | *1 |  |  |

*1 $\mathrm{t}_{\text {OScon }}$ depends on the type of crystal or resonator.
Refer to characteristic data of crystal or resonator used.

## AC Characteristics-2

$\left(\mathrm{V}_{\mathrm{DD}}, \mathrm{V}_{\mathrm{DISP}}=3.3 \mathrm{~V} \pm 10 \%, \mathrm{~V}_{\mathrm{FL}}=-60 \mathrm{~V}, \mathrm{Ta}=-40\right.$ to $+85^{\circ} \mathrm{C}$, unless otherwise specified)

| Parameter | Symbol |  | Condition | Min. | Max. | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\overline{\mathrm{CP}}$ Frequency | $\mathrm{f}_{\mathrm{c}}$ |  | - | - | 2.0 | MHz |
| $\overline{\overline{C P}}$ Pulse Width | $\mathrm{t}_{\mathrm{cw}}$ |  | - | 250 | - | ns |
| DA Setup Time | $t_{\text {DS }}$ |  | - | 250 | - | ns |
| DA Hold Time | $\mathrm{t}_{\mathrm{DH}}$ |  | - | 250 | - | ns |
| $\overline{\text { CS Setup Time }}$ | $\mathrm{t}_{\text {css }}$ |  | - | 250 | - | ns |
| $\overline{\text { CS }}$ Hold Time | $\mathrm{t}_{\text {cSH }}$ |  | f-oscillation | 16 | - | $\mu \mathrm{s}$ |
| $\overline{\text { CS Wait Time }}$ | $\mathrm{t}_{\text {csw }}$ |  | - | 250 | - | ns |
| Data Processing Time | $\mathrm{t}_{\text {DOFF }}$ |  | f-oscillation | 8 | - | $\mu \mathrm{s}$ |
| RESET Pulse Width | $\mathrm{t}_{\text {WRES }}$ | When $\bar{R}$ microc | signal is input from oller, etc. externally | 250 | - | ns |
| $\overline{\mathrm{RESET}}$ Time | $\mathrm{t}_{\text {RSON }}$ |  | - | $\mathrm{t}_{\text {Oscon }}$ | - | ns |
| DA Wait Time | $\mathrm{t}_{\text {RSOFF }}$ |  | - | 250 | - | ns |
| All Output Slew Rate | $\mathrm{t}_{\mathrm{R}}$ | $\mathrm{C}_{1}=100 \mathrm{pF}$ | $\mathrm{t}_{\mathrm{R}}=20 \%$ to $80 \%$ | - | 2.0 | $\mu \mathrm{s}$ |
|  | $\mathrm{t}_{\mathrm{F}}$ |  | $\mathrm{t}_{\mathrm{F}}=80 \%$ to $20 \%$ | - | 2.0 | $\mu \mathrm{s}$ |
| OSC Duty Ratio | $\mathrm{du}_{\text {osc }}$ |  | - | 40 | 60 | \% |
| Oscillation Start-up time | $\mathrm{t}_{\text {OSCon }}$ |  | - | *1 |  |  |

*1 $\mathrm{t}_{\text {OSCoN }}$ depends on the type of crystal or resonator.
Refer to characteristic data of crystal or resonator used.

## TIMING DIAGRAM

| Symbol | $\mathrm{V}_{\mathrm{DD}}=3.3 \mathrm{~V} \pm 10 \%$ | $\mathrm{~V}_{\mathrm{DD}}=5.0 \mathrm{~V} \pm 10 \%$ |
| :---: | :---: | :---: |
| $\mathrm{~V}_{\mathrm{H}}$ | $0.8 \mathrm{~V}_{\mathrm{DD}}$ | $0.7 \mathrm{~V}_{\mathrm{DD}}$ |
| $\mathrm{V}_{\mathrm{IL}}$ | $0.2 \mathrm{~V}_{\mathrm{DD}}$ | $0.3 \mathrm{~V}_{\mathrm{DD}}$ |

- Data Timing

- Reset Timing

- Output Timing

- Digit Output Timing (for 16-digit display, at a duty of 960/1024)

- OSC Timing



## FUNCTIONAL DESCRIPTION

## Commands List

|  | Command | LSB |  |  | 1st byte |  |  | MSB |  | LS |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | B0 | B1 | B2 | B3 | B4 | B5 | B6 | B7 | B |
| 1 | DCRAM data write | X0 | X1 | X2 | X3 | X4 | 1 | 0 | 0 | c |
| 2 | CGRAM data write | X0 | X1 | X2 | X3 | * | 0 | 1 | 0 | C |
| 3 | ADRAM data write | X0 | X1 | X2 | X3 | X4 | 1 | 1 | 0 | c |
| 4 | General output port set | P1 | P2 | P3 | P4 | * | 0 | 0 | 1 |  |
| 5 | Display duty set | D0 | D1 | * | * | * | 1 | 0 | 1 | D |
| 6 | Number of digits set | K0 | K1 | K2 | K3 | * | 0 | 1 | 1 |  |
| 7 | All lights ON/OFF | L | H | * | * | * | 1 | 1 | 1 |  |
|  | Test mode |  |  |  |  |  |  |  |  |  |

* : Don't care

Xn : Address specification for each RAM
Cn : Character code specification for each RAM
Pn : General output port status specification
Dn : Display duty specification
Kn : Number of digits specification
H : All lights ON instruction
L : All lights OFF instruction
When data is written to RAM (DCRAM, CGRAM, ADRAM) continuously, addresses are internally incremented automatically.
Therefore it is not necessary to specify the 1st byte to write RAM data for the 2 nd and later bytes.

Note: The test mode is used for inspection before shipment. It is not a user function.

## Positional Relationship Between SEGn and ADn (one digit)



## Data Transfer Method and Command Write Method

Display control command and data are written by an 8-bit serial transfer. Write timing is shown in the figure below.

Setting the $\overline{\mathrm{CS}}$ pin to "Low" level enables a data transfer.
Data is 8 bits and is sequentially input into the DA pin from LSB (LSB first).
As shown in the figure below, data is read by the shift register at the rising edge of the shift clock, which is input into the $\overline{\mathrm{CP}}$ pin. If 8-bit data is input, internal load signals are automatically generated and data is written to each register and RAM.
Therefore it is not necessary to input load signals from the outside.
Setting the $\overline{\mathrm{CS}}$ pin to "High" disables data transfer. Data input from the point when the $\overline{\mathrm{CS}}$ pin changes from "High" to "Low" is recognized in 8-bit units.


* When data is written to RAM (DCRAM, ADRAM, CGRAM) continuously, addresses are internally incremented automatically.
Therefore it is not necessary to specify the 1 st byte to write RAM data for the 2 nd and later bytes.


## Reset Function

Reset is executed when the $\overline{\text { RESET }}$ pin is set to "L", (when turning power on, for example) and initializes all functions.
Initial status is as follows:

- Address of each RAM address " 00 "H
- Data of each RAM

All contents are undefined

- General output port............................................ All general output ports (P1 to P4) go "Low"
- Display digit

24 digits

- Brightness adjustment.

0/1024

- All display lights ON or OFF

OFF mode

- Segment output

All segment outputs (SEG1 to SEG35) go "Low"

- Common output

All common outputs (COM1 to COM24) go "Low"

- AD output All AD outputs (AD1 to AD4) go "Low"
Please set the functions again according to "Setting Flowchart" after reset.


## Description of Commands and Functions

1. DCRAM data write
(Specifies the addresses 00 H to 1 FH of DCRAM and writes the character codes of CGROM and CGRAM.)
DCRAM (Data Control RAM) has a 5-bit address to store the character codes of CGROM and CGRAM. The character code specified by DCRAM is converted to a $5 \times 7$ dot matrix character pattern via CGROM or CGRAM.
(The DCRAM can store 24 characters.)
[Command format]


To specify the character code of CGROM and CGRAM continuously to the next address, specify only character codes as follows.
The addresses of DCRAM are automatically incremented. Specification of an address is unnecessary.

|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ | specifies the character codes of CGROM and CGRAM (written into DCRAM address 01H) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2nd byte (3rd) | CO | C1 | C2 | C3 | C4 | C5 | C6 | C7 |  |
|  | $\begin{aligned} & \text { LSB } \\ & \text { B0 } \end{aligned}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ |  |
| 2nd byte (4th) | C0 | C1 | C2 | C3 | C4 | C5 | C6 | C7 | specifies the character codes of CGROM and CGRAM (written into DCRAM address 02H) |
|  |  |  |  |  |  |  |  |  |  |
|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ |  |
| 2nd byte (25th) | CO | C1 | C2 | C3 | C4 | C5 | C6 | C7 | specifies the character codes of CGROM and CGRAM (written into DCRAM address 17H) |

The character code setting of CGROM and CGRAM up to 24 digits is completed.
To set a character code from DCRAM address 00H continuously.
Specify a dummy charactor code between DCRAM addresses 18H and 1FH.
(To increament the DCRAM address automatically and set it to 00 H )

|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 |  | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ | specifies the character codes of dummy CGROM and CGRAM <br> (Not written into DCRAM address) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2nd byte (26th) | CO | C1 | C2 | C3 | C4 | C5 | C6 | C7 |  |
|  |  |  |  |  |  | Opera | 8 | mes) |  |
|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 |  | MSB |  |
| 2nd byte (33th) | CO | C1 | C2 | C3 | C4 | C5 | C6 | C7 | specifies the character codes of dummy CGROM and CGRAM <br> (Not written into DCRAM address) |
|  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  |  |  |  |  |
|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ |  |
| 2nd byte (34th) | CO | C1 | C2 | C3 | C4 | C5 | C6 | C7 | specifies the character codes of CGROM and CGRAM (DCRAM address 00 H is rewritten) |

X0 (LSB) to X4 (MSB): DCRAM addresses (5 bits: 24 characters)
C0 (LSB) to C7 (MSB): Character codes of CGROM and CGRAM (8 bits: 256 characters)
[COM positions and set DCRAM addresses]

| HEX | X0 | X1 | X2 | X3 | X4 | COM position | HEX | X0 | X1 | X2 | X3 | X4 | COM position |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 0 | 0 | 0 | 0 | 0 | COM1 | 10 | 0 | 0 | 0 | 0 | 1 | COM17 |
| 01 | 1 | 0 | 0 | 0 | 0 | COM2 | 11 | 1 | 0 | 0 | 0 | 1 | COM18 |
| 02 | 0 | 1 | 0 | 0 | 0 | COM3 | 12 | 0 | 1 | 0 | 0 | 1 | COM19 |
| 03 | 1 | 1 | 0 | 0 | 0 | COM4 | 13 | 1 | 1 | 0 | 0 | 1 | COM20 |
| 04 | 0 | 0 | 1 | 0 | 0 | COM5 | 14 | 0 | 0 | 1 | 0 | 1 | COM21 |
| 05 | 1 | 0 | 1 | 0 | 0 | COM6 | 15 | 1 | 0 | 1 | 0 | 1 | COM22 |
| 06 | 0 | 1 | 1 | 0 | 0 | COM7 | 16 | 0 | 1 | 1 | 0 | 1 | COM23 |
| 07 | 1 | 1 | 1 | 0 | 0 | COM8 | 17 | 1 | 1 | 1 | 0 | 1 | COM24 |
| 08 | 0 | 0 | 0 | 1 | 0 | COM9 | 18 | 0 | 0 | 0 | 1 | 1 | Not fixed |
| 09 | 1 | 0 | 0 | 1 | 0 | COM10 | 19 | 1 | 0 | 0 | 1 | 1 | Not fixed |
| 0A | 0 | 1 | 0 | 1 | 0 | COM11 | 1 A | 0 | 1 | 0 | 1 | 1 | Not fixed |
| 0B | 1 | 1 | 0 | 1 | 0 | COM12 | $1 B$ | 1 | 1 | 0 | 1 | 1 | Not fixed |
| 0C | 0 | 0 | 1 | 1 | 0 | COM13 | $1 C$ | 0 | 0 | 1 | 1 | 1 | Not fixed |
| 0D | 1 | 0 | 1 | 1 | 0 | COM14 | 1D | 1 | 0 | 1 | 1 | 1 | Not fixed |
| 0E | 0 | 1 | 1 | 1 | 0 | COM15 | $1 E$ | 0 | 1 | 1 | 1 | 1 | Not fixed |
| 0F | 1 | 1 | 1 | 1 | 0 | COM16 | $1 F$ | 1 | 1 | 1 | 1 | 1 | Not fixed |

2. CGRAM data write
(Specifies the addresses of CGRAM and writes character pattern data.)
CGRAM (Character Generator RAM) has a 4-bit address to store $5 \times 7$ dot matrix character patterns.
A character pattern stored in CGRAM can be displayed by specifying the character code (address) by DCRAM.
The address of CGRAM is assigned to 00 H to 0 FH . (All the other addresses are the CGROM addresses.) (The CGRAM can store 16 types of character patterns.)
[Command format]

selects CGRAM data write mode and specifies CGRAM address.
(Ex: Specifies CGRAM address 00H.)
specifies 1st column data
(written into CGRAM address 00H)

specifies 2nd column data
(written into CGRAM address 00H)

|  | $\begin{aligned} & \text { LSB } \\ & \text { BO } \end{aligned}$ | B1 | B2 B3 | B4 | B5 | B6 |  | $\begin{aligned} & \text { ISB } \\ & 37 \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 4th byte | C2 | C7 | C12C17 | C22 | C27 |  |  |  |

specifies 3rd column data (written into CGRAM address 00H)

specifies 4th column data (written into CGRAM address 00 H )
specifies 5th column data (written into CGRAM address 00H)

To specify character pattern data continuously to the next address, specify only character pattern data as follows. The addresses of CGRAM are automatically incremented. Specification of an address is therefore unnecessary. The 2 nd to 6 th byte (character pattern data) are regarded as one data item, so 250 ns is sufficient for $\mathrm{t}_{\text {Doff }}$ time between bytes.


X0 (LSB) to X3 (MSB) : CGRAM addresses (4 bits: 16 characters)
C 0 (LSB) to C 34 (MSB) : Character pattern data ( 35 bits: 35 outputs per digit)

* : Don't care
[CGROM addresses and set CGRAM addresses]
Refer to ROMCODE table

| HEX | X0 | X1 | X2 | X3 | CGROM address | HEX | X0 | X1 | X2 | X3 | CGROM address |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 0 | 0 | 0 | 0 | RAM00(00000000B) | 08 | 0 | 0 | 0 | 1 | RAM08(00001000B) |
| 01 | 1 | 0 | 0 | 0 | RAM01(00000001B) | 09 | 1 | 0 | 0 | 1 | RAM09(00001001B) |
| 02 | 0 | 1 | 0 | 0 | RAM02(00000010B) | OA | 0 | 1 | 0 | 1 | RAM0A(00001010B) |
| 03 | 1 | 1 | 0 | 0 | RAM03(00000011B) | $0 B$ | 1 | 1 | 0 | 1 | RAM0B(00001011B) |
| 04 | 0 | 0 | 1 | 0 | RAM04(00000100B) | $0 C$ | 0 | 0 | 1 | 1 | RAM0C(00001100B) |
| 05 | 1 | 0 | 1 | 0 | RAM05(00000101B) | $0 D$ | 1 | 0 | 1 | 1 | RAM0D(00001101B) |
| 06 | 0 | 1 | 1 | 0 | RAM06(00000110B) | 0E | 0 | 1 | 1 | 1 | RAM0E(00001110B) |
| 07 | 1 | 1 | 1 | 0 | RAM07(00000111B) | OF | 1 | 1 | 1 | 1 | RAM0F(00001111B) |

Positional relationship between the output area of CGROM and that of CGRAM


Note: $\quad$ CGROM (Character Generator ROM) has an 8 -bit address to generate $5 \times 7$ dot matrix character patterns.
CGRAM can store 240 types of character patterns.
General-purpose code -01 is available and custom codes are provided on customer's request.
3. ADRAM data write
(Specifies the addresses 00 H to 1 FH of ADRAM and writes symbol data.)
ADRAM (Additional Data RAM) has a 5-bit address to store symbol data.
Symbol data specified by ADRAM is directly output without CGROM and CGRAM.
(The ADRAM can store 4 types of symbol patterns for each digit.)
The terminal to which the contents of ADRAM are output can be used as a cursor.
[Command format]


To specify symbol data continuously to the next address, specify only symbol data as follows.
The address of ADRAM is automatically incremented. Specification of addresses is therefore unnecessary.


The symbol data setting up to 24 digits is completed.
To set symbol data from ADRAM address 00 H continuously.
Specify a dummy symbol data between ADRAM addresses 18 H and 1 FH .
(To increment the ADRAM address automatically and set it to 00 H )

| 2nd byte (26th) | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ |  |  | B3 |  | B5 |  | $\begin{aligned} & \text { MSB } \\ & \text { R7 } \end{aligned}$ | sets dummy symbol data (Not written into ADRAM address) |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | C0 | C1 | C2 | C3 | * | * | * | * |  |
|  |  |  |  |  |  |  |  |  |  |
| 2nd byte (33th) | $\begin{gathered} \text { LSB } \\ \text { BO } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{aligned} & \text { MSB } \\ & \text { B7 } \end{aligned}$ | sets dummy symbol data (Not written into ADRAM address) |
|  | CO | C1 | C2 | C3 | * | * | * | * |  |
|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 |  | $\begin{aligned} & \text { MSB } \\ & \text { B7 } \end{aligned}$ |  |
| 2nd byte (34th) | C0 | C1 | C2 | C3 | * | * | * | * | sets dummy symbol data (ADRAM address 00 H is rewritten) |

X0 (LSB) to X4 (MSB)
C 0 (LSB) to C3 (MSB)
: ADRAM addresses (5 bits: 24 characters)
: Symbol data (4 bits: 4-symbol data per digit)
: Don't care
[COM positions and ADRAM addresses]

| HEX | X0 | X1 | X2 | X3 | X4 | COM position | HEX | X0 | X1 | X2 | X3 | X4 | COM position |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 00 | 0 | 0 | 0 | 0 | 0 | COM1 | 10 | 0 | 0 | 0 | 0 | 1 | COM17 |
| 01 | 1 | 0 | 0 | 0 | 0 | COM2 | 11 | 1 | 0 | 0 | 0 | 1 | COM18 |
| 02 | 0 | 1 | 0 | 0 | 0 | COM3 | 12 | 0 | 1 | 0 | 0 | 1 | COM19 |
| 03 | 1 | 1 | 0 | 0 | 0 | COM4 | 13 | 1 | 1 | 0 | 0 | 1 | COM20 |
| 04 | 0 | 0 | 1 | 0 | 0 | COM5 | 14 | 0 | 0 | 1 | 0 | 1 | COM21 |
| 05 | 1 | 0 | 1 | 0 | 0 | COM6 | 15 | 1 | 0 | 1 | 0 | 1 | COM22 |
| 06 | 0 | 1 | 1 | 0 | 0 | COM7 | 16 | 0 | 1 | 1 | 0 | 1 | COM23 |
| 07 | 1 | 1 | 1 | 0 | 0 | COM8 | 17 | 1 | 1 | 1 | 0 | 1 | COM24 |
| 08 | 0 | 0 | 0 | 1 | 0 | COM9 | 18 | 0 | 0 | 0 | 1 | 1 | Not fixed |
| 09 | 1 | 0 | 0 | 1 | 0 | COM10 | 19 | 1 | 0 | 0 | 1 | 1 | Not fixed |
| 0A | 0 | 1 | 0 | 1 | 0 | COM11 | 1 A | 0 | 1 | 0 | 1 | 1 | Not fixed |
| OB | 1 | 1 | 0 | 1 | 0 | COM12 | $1 B$ | 1 | 1 | 0 | 1 | 1 | Not fixed |
| 0C | 0 | 0 | 1 | 1 | 0 | COM13 | $1 C$ | 0 | 0 | 1 | 1 | 1 | Not fixed |
| 0D | 1 | 0 | 1 | 1 | 0 | COM14 | $1 D$ | 1 | 0 | 1 | 1 | 1 | Not fixed |
| 0E | 0 | 1 | 1 | 1 | 0 | COM15 | $1 E$ | 0 | 1 | 1 | 1 | 1 | Not fixed |
| 0F | 1 | 1 | 1 | 1 | 0 | COM16 | $1 F$ | 1 | 1 | 1 | 1 | 1 | Not fixed |

4. General output port set
(Specifies the general output port status.)
The general output port is an output for 4-bit static operation.
When the $\overline{\mathrm{RESET}}$ signal is input, the general output ports go "Low". (see "Reset Function")
It is used to control other I/O devices and turn on LED. (static operation)
When at the "High" level, this output becomes the $\mathrm{V}_{\mathrm{DD}}$ voltage, and when at the "Low" level, it becomes the ground potential. Therefore, the fluorescent display tube cannot be driven.
[Command format]

|  | $\begin{aligned} & \text { LSB } \\ & \text { R } R_{1} \end{aligned}$ |  | B2 | B3 | B4 | B5 | $\begin{array}{r}  \\ \\ \text { B6 } \end{array}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1st byte | P1 | P2 | P3 | P4 | * | 0 | 0 | 1 |

: selects a general output port and specifies the output status

P1 to P4 : general output ports

* : Don't care
[Set data and set state of general output port]

| Pn | Display state of general output port |
| :---: | :---: |
| 0 | Sets the output to Low |
| (The state when $\overline{\text { RESET signal is input.) }}$ <br> 1$\quad$ Sets the output to High |  |

5. Display duty set
(Writes a display duty value to the duty cycle register.)
Display duty adjusts brightness in 960 stages ( $0 / 1024$ to $960 / 1024$ ) using 10-bit data.
When the RESET signal is input, the duty cycle register value is "0". (see "Reset Function") Always execute this instruction before turning the display on, then set a desired duty value.
[Command format]


|  | $\begin{gathered} \text { LSB } \\ \text { B0 } \end{gathered}$ | B1 | B2 | B3 | B4 | B5 | B6 | $\begin{gathered} \text { MSB } \\ \text { B7 } \end{gathered}$ |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 2nd byte (2nd) | D2 | D3 | D4 | D5 | D6 | D7 | D8 | D9 |  | ets duty value (high-order 8 bits). |

D0 (LSB) to D9 (MSB) : display duty data (10 bits: 0/1024 to 960/1024 stages)

* : Don't care
[Relation between setup data and controlled COM duty]

| HEX | D0 | D1 | D2 | D3 | D4 | D5 | D6 | D7 | D8 | D9 | COM duty |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 000 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $0 / 1024$ |
| 001 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $1 / 1024$ |
| 002 | 0 | 1 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | $2 / 1024$ |
| $\vdots$ |  |  |  |  |  |  |  |  |  |  | $\vdots$ |
| $3 B E$ | 0 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | $958 / 1024$ |
| 3BF | 1 | 1 | 1 | 1 | 1 | 1 | 0 | 1 | 1 | 1 | $959 / 1024$ |
| 3C0 | 0 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | $960 / 1024$ |
| $3 C 1$ | 1 | 0 | 0 | 0 | 0 | 0 | 1 | 1 | 1 | 1 | $960 / 1024$ |
| $\vdots$ |  |  |  |  |  |  |  |  |  |  | $\vdots$ |
| 3FE | 0 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | $960 / 1024$ |
| 3FF | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 | $960 / 1024$ |

$\leftarrow$ (The state when $\overline{\text { RESET signal is }}$ input.)
6. Number of digits set
(Writes the number of display digits to the display digit register.)
The number of digits set can display 9 to 24 digits using 4-bit data.
When the RESET signal is input, the number of digit register value is " 0 ". (see "Reset Function") Always execute this instruction to change the number of digits before turning the display on.
[Command format]

: selects the number of digit set mode and specifies the number of digit value

K0 (LSB) to K3 (MSB) : number of digit data (4 bits: 16 digits)
: Don't care
[Relation between setup data and controlled COM]

| HEX | K0 | K1 | K2 | K3 | Number of digits <br> of COM | HEX | K0 | K1 | K2 | K3 | Number of digits <br> of COM |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | 0 | 0 | 0 | 0 | COM1 to 24 | 8 | 0 | 0 | 0 | 1 | COM1 to 16 |
| 1 | 1 | 0 | 0 | 0 | COM1 to 9 | 9 | 1 | 0 | 0 | 1 | COM1 to 17 |
| 2 | 0 | 1 | 0 | 0 | COM1 to 10 | A | 0 | 1 | 0 | 1 | COM1 to 18 |
| 3 | 1 | 1 | 0 | 0 | COM1 to 11 | B | 1 | 1 | 0 | 1 | COM1 to 19 |
| 4 | 0 | 0 | 1 | 0 | COM1 to 12 | C | 0 | 0 | 1 | 1 | COM1 to 20 |
| 5 | 1 | 0 | 1 | 0 | COM1 to 13 | D | 1 | 0 | 1 | 1 | COM1 to 21 |
| 6 | 0 | 1 | 1 | 0 | COM1 to 14 | E | 0 | 1 | 1 | 1 | COM1 to 22 |
| 7 | 1 | 1 | 1 | 0 | COM1 to 15 | F | 1 | 1 | 1 | 1 | COM1 to 23 |

* The state when $\overline{\text { RESET }}$ signal is input.

7. All display lights ON/OFF set
(Turns all display lights ON or OFF.)
When the RESET signal is input, all segment, common and AD outputs go "Low". (see "Reset Function") All display lights ON is used primarily for display testing.
All display lights OFF is primarily used for display blink and to prevent malfunction when power is turned on. This command cannot control the general output port.
[Command format]

[Set data and display state of SEG and AD]

| L | $H$ | Display state of SEG and AD |
| :--- | :--- | :--- |
| 0 | 0 | Normal display |
| 1 | 0 | Sets all outputs to Low |
| 0 | 1 | Sets all outputs to High |
| 1 | 1 | Sets all outputs to High |$\quad$|  |
| :--- |

## Setting Flowchart

(Power applying included)


## Power-off Flowchart



## APPLICATION CIRCUIT



Notes: *1. The application circuit indicates a circuit by which fluorescent display tube filaments are ac driven using a heater transformer. Contact fluorescent display tube manufacturers for the methods and circuits of driving fluorescent display tube filaments.
*2. Keep the wires between the OSC0 pin and the crystal or ceramic resonator as short as possible to avoid generating noise.
*3 For oscillation capacitor values, refer to data of the crystal or ceramic resonator used.

## REFERENCE DATA

Graphs illustrating the $\mathrm{V}_{\mathrm{FL}}$ versus driver output current capability relationship are shown below.
Care must be taken not to use the total power in excess of allowable power dissipation.
[Driver output current versus output drop voltage]
$\mathrm{V}_{\mathrm{FL}}=-60 \mathrm{~V}, \mathrm{COMn}$
[Output current (mA)]

(V)

Driver output current versus output drop voltage]
$\mathrm{VFL}=-20 \mathrm{~V}, \mathrm{COMn}$
[Output current (mA)]

(V)
[Driver output current versus output drop voltage]
VFL $=-60 \mathrm{~V}$, ADn
[Output current (mA)]

(V)

Driver output current versus output drop voltage]
VFL $=-20 \mathrm{~V}$, ADn
[Output current (mA)]

(V)

Driver output current versus output drop voltage] VFL = -20V, SEGn
[Output current (mA)]

(V)

## ML9207-01 ROM CODE

$00000000 \mathrm{~B}(00 \mathrm{H})$ to $00000111 \mathrm{~B}(0 \mathrm{FH})$ are the CGRAM addresses.


## PACKAGE DIMENSIONS

(Unit: mm)


Notes for Mounting the Surface Mount Type Package
The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage.
Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).
(Unit: mm)


Notes for Mounting the Surface Mount Type Package
The surface mount type packages are very susceptible to heat in reflow mounting and humidity absorbed in storage.
Therefore, before you perform reflow mounting, contact Oki's responsible sales person for the product name, package name, pin number, package code and desired mounting conditions (reflow method, temperature and times).

## NOTICE

1. The information contained herein can change without notice owing to product and/or technical improvements. Before using the product, please make sure that the information being referred to is up-to-date.
2. The outline of action and examples for application circuits described herein have been chosen as an explanation for the standard action and performance of the product. When planning to use the product, please ensure that the external conditions are reflected in the actual circuit, assembly, and program designs.
3. When designing your product, please use our product below the specified maximum ratings and within the specified operating ranges including, but not limited to, operating voltage, power dissipation, and operating temperature.
4. Oki assumes no responsibility or liability whatsoever for any failure or unusual or unexpected operation resulting from misuse, neglect, improper installation, repair, alteration or accident, improper handling, or unusual physical or electrical stress including, but not limited to, exposure to parameters beyond the specified maximum ratings or operation outside the specified operating range.
5. Neither indemnity against nor license of a third party's industrial and intellectual property right, etc. is granted by us in connection with the use of the product and/or the information and drawings contained herein. No responsibility is assumed by us for any infringement of a third party's right which may result from the use thereof.
6. The products listed in this document are intended for use in general electronics equipment for commercial applications (e.g., office automation, communication equipment, measurement equipment, consumer electronics, etc.). These products are not authorized for use in any system or application that requires special or enhanced quality and reliability characteristics nor in any system or application where the failure of such system or application may result in the loss or damage of property, or death or injury to humans. Such applications include, but are not limited to, traffic and automotive equipment, safety devices, aerospace equipment, nuclear power control, medical equipment, and life-support systems.
7. Certain products in this document may need government approval before they can be exported to particular countries. The purchaser assumes the responsibility of determining the legality of export of these products and will take appropriate and necessary steps at their own expense for these.
8. No part of the contents contained herein may be reprinted or reproduced without our prior permission.

Copyright 2000 Oki Electric Industry Co., Ltd.

