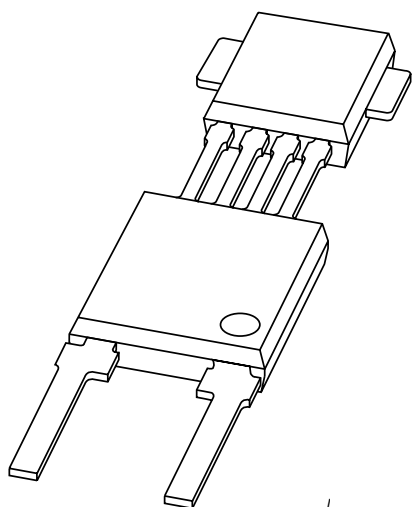


**DISCRETE SEMICONDUCTORS**

# DATA SHEET



## **KMI15/2**

### **Integrated rotational speed sensor**

Product specification  
Supersedes data of 1996 Dec 05  
File under Discrete Semiconductors, SC17

1998 Mar 25

## Integrated rotational speed sensor

KMI15/2

## FEATURES

- Digital current output signal
- Zero speed capability
- Wide air gap
- Wide temperature range
- Insensitive to vibration
- EMC resistant.

## DESCRIPTION

The KMI15/2 sensor detects (rotational) speed and reference mark detection of magnetized targets<sup>(1)</sup>. The sensor consists of a magnetoresistive sensor element, a signal conditioning integrated circuit in bipolar technology and a magnetized ferrite magnet. The frequency of the digital current output signal is proportional to the rotational speed of a gear wheel.

## CAUTION

Do not press two or more products together against their magnetic forces.

(1) The sensor contains a customized integrated circuit. Usage in hydraulic brake systems and in systems with active brake control is forbidden.

## PINNING

| PIN | DESCRIPTION     |
|-----|-----------------|
| 1   | V <sub>CC</sub> |
| 2   | V <sub>-</sub>  |

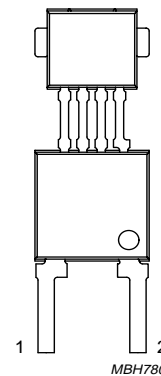


Fig.1 Simplified outline; (SOT453A).

## QUICK REFERENCE DATA

| SYMBOL                 | PARAMETER                     | MIN. | TYP. | MAX.  | UNIT |
|------------------------|-------------------------------|------|------|-------|------|
| V <sub>CC</sub>        | DC supply voltage             | 0.5  | 12   | 16    | V    |
| I <sub>CC (low)</sub>  | current output signal low     | –    | 7    | –     | mA   |
| I <sub>CC (high)</sub> | current output signal high    | –    | 14   | –     | mA   |
| f <sub>t</sub>         | operating frequency           | 0    | –    | 25000 | Hz   |
| T <sub>amb</sub>       | ambient operating temperature | –40  | –    | +85   | °C   |

## Integrated rotational speed sensor

KMI15/2

**LIMITING VALUES**

In accordance with Absolute Maximum Rating System (IEC 134).

| SYMBOL    | PARAMETER                            | CONDITIONS  | MIN.       | MAX. | UNIT |
|-----------|--------------------------------------|---|------------|------|------|
| $V_{CC}$  | DC supply voltage                    | $T_{amb} = -40$ to $+85$ °C; $R_L = 115$ $\Omega$ | 0.5        | 16   | V    |
| $T_{stg}$ | storage temperature                  |   | -40        | +150 | °C   |
| $T_{amb}$ | operating ambient temperature        |   | -40        | +85  | °C   |
| $T_{sld}$ | soldering temperature                | $t \leq 10$ s                                     | -          | 260  | °C   |
|           | output short-circuit duration to GND |   | continuous |      |      |

**CHARACTERISTICS** $T_{amb} = 25$  °C;  $V_{CC} = 12$  V;  $f_t = 2$  kHz; test circuit: see Fig.7;  $R_L = 115$   $\Omega$ .

| SYMBOL          | PARAMETER                         | CONDITIONS  | MIN. | TYP. | MAX.  | UNIT    |
|-----------------|-----------------------------------|---|------|------|-------|---------|
| $I_{CC (low)}$  | current output signal low         | see Fig.6   | 5.6  | 7.0  | 8.4   | mA      |
| $I_{CC (high)}$ | current output signal high        | see Fig.6   | 11.2 | 14.0 | 16.8  | mA      |
| $t_r$           | output signal rise time           | $C_L = 100$ pF; 10 to 90% value                                   | -    | 0.5  | -     | $\mu$ s |
| $t_f$           | output signal fall time           | $C_L = 100$ pF; 10 to 90% value                                   | -    | 0.7  | -     | $\mu$ s |
| $t_d$           | switching delay time              | between stimulation pulse (generated by a coil) and output signal | -    | 1    | -     | $\mu$ s |
| $f_t$           | operating frequency               | for both rotation directions                                      | 0    | -    | 25000 | Hz      |
| $H_{sLH}$       | magnetic switching field strength |   | 0.05 | 0.3  | 0.8   | kA/m    |
| $H_{sHL}$       | magnetic switching field strength |   | 0.05 | 0.3  | 0.8   | kA/m    |
| $H_s$           | magnetic switching hysteresis     |   | 0.15 | -    | 1.6   | kA/m    |

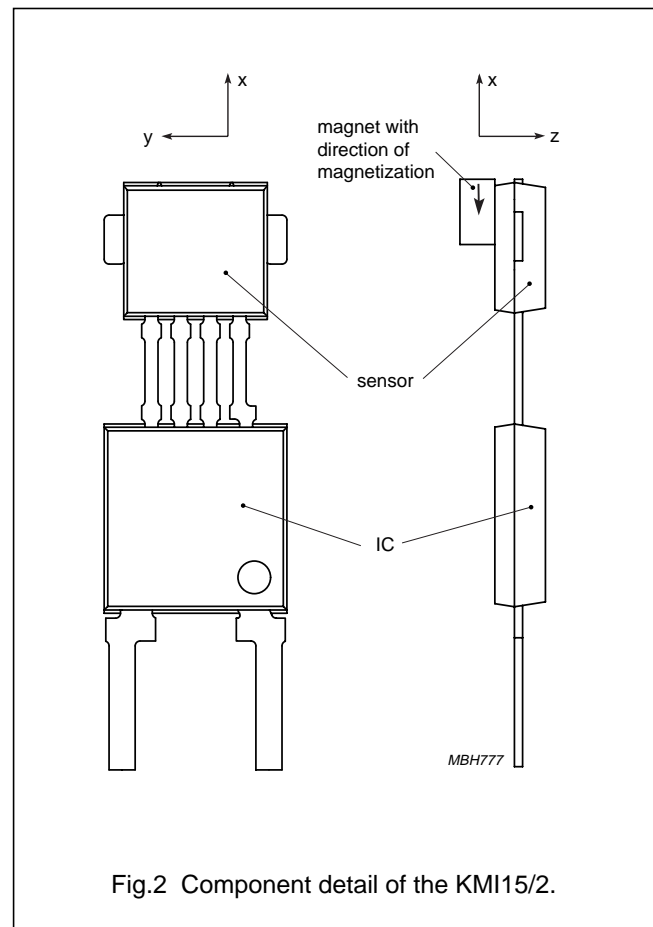
## Integrated rotational speed sensor

KMI15/2

**FUNCTIONAL DESCRIPTION**

The KMI15/2 sensor is sensitive to magnetic fields. The functional principle is shown in Fig.3. The field lines of a magnetized target are shown in Fig.3 as a straight target (it could also be circular e.g. for rotational speed measurement). If a sensor KMI15/2 is moved as shown in this field, either of the magnetic field components  $H_{sHL}$  or  $H_{sLH}$  is dominant, and forces the sensor to switch to either the high current (14 mA) or to the low current (7 mA). Oscillation of the sensor output signal is avoided by the implementation of a hysteresis into the signal conditioning electronic.

The MR sensor is stabilized by a permanent magnet applying a continuous magnetic field of  $\geq 6$  kA/m to the sensor. If the magnetic field given by the magnetized target errors like frequency doubling might occur. The magnetoresistive sensor element signal is amplified, temperature compensated and forwarded to a Schmitt-trigger in the conditioning integrated circuit (Figs 4 and 5). The digital output signal levels (Fig.6) are independent of the magnetic field condition. A (2-wire) output current enables safe transfer of the sensor signal to the detecting circuit (Fig.7). The integrated circuit housing is separated from the sensor element housing to optimize the sensor behaviour at high temperatures.



Integrated rotational speed sensor

KMI15/2

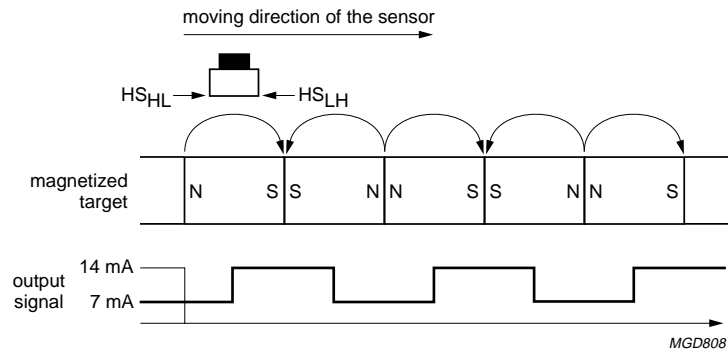


Fig.3 Functional principle of KMI15/2.

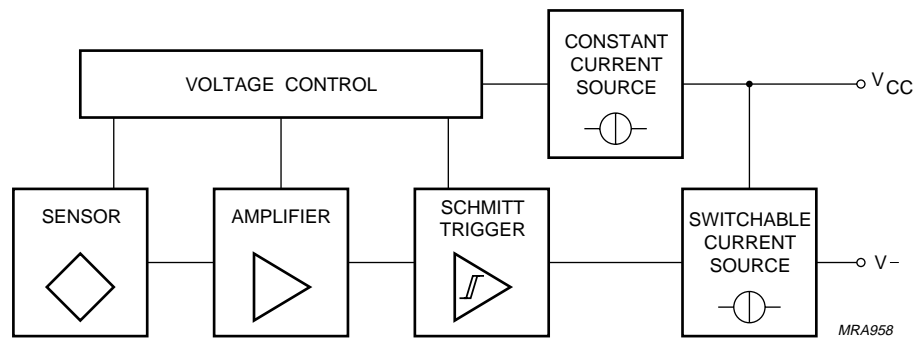
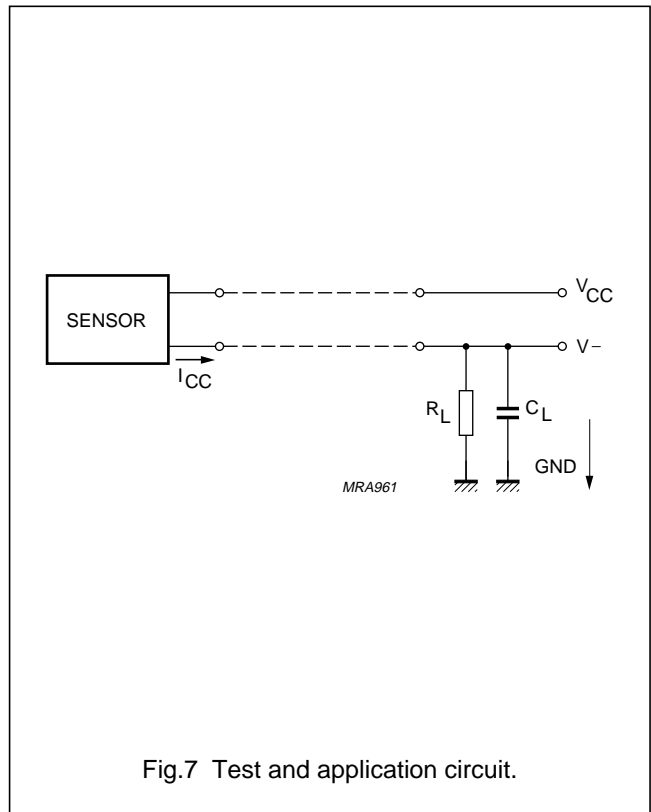
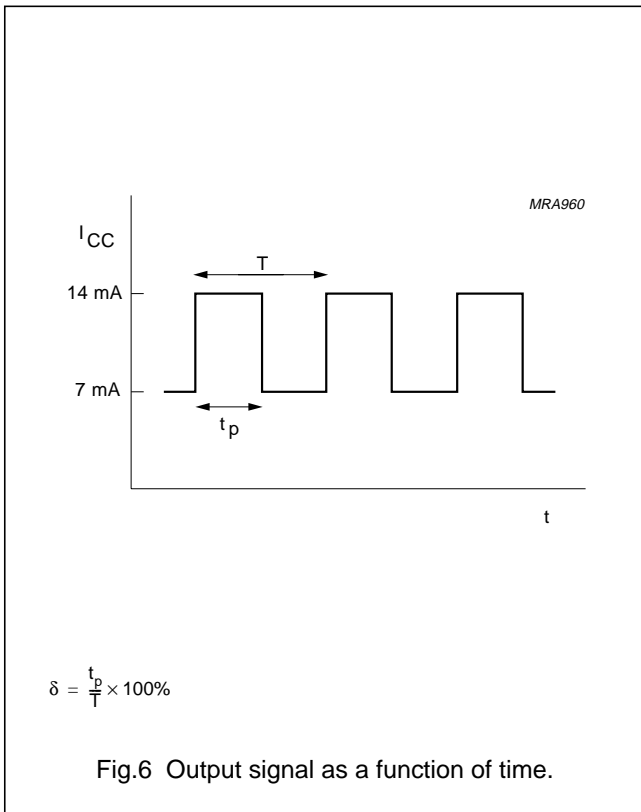
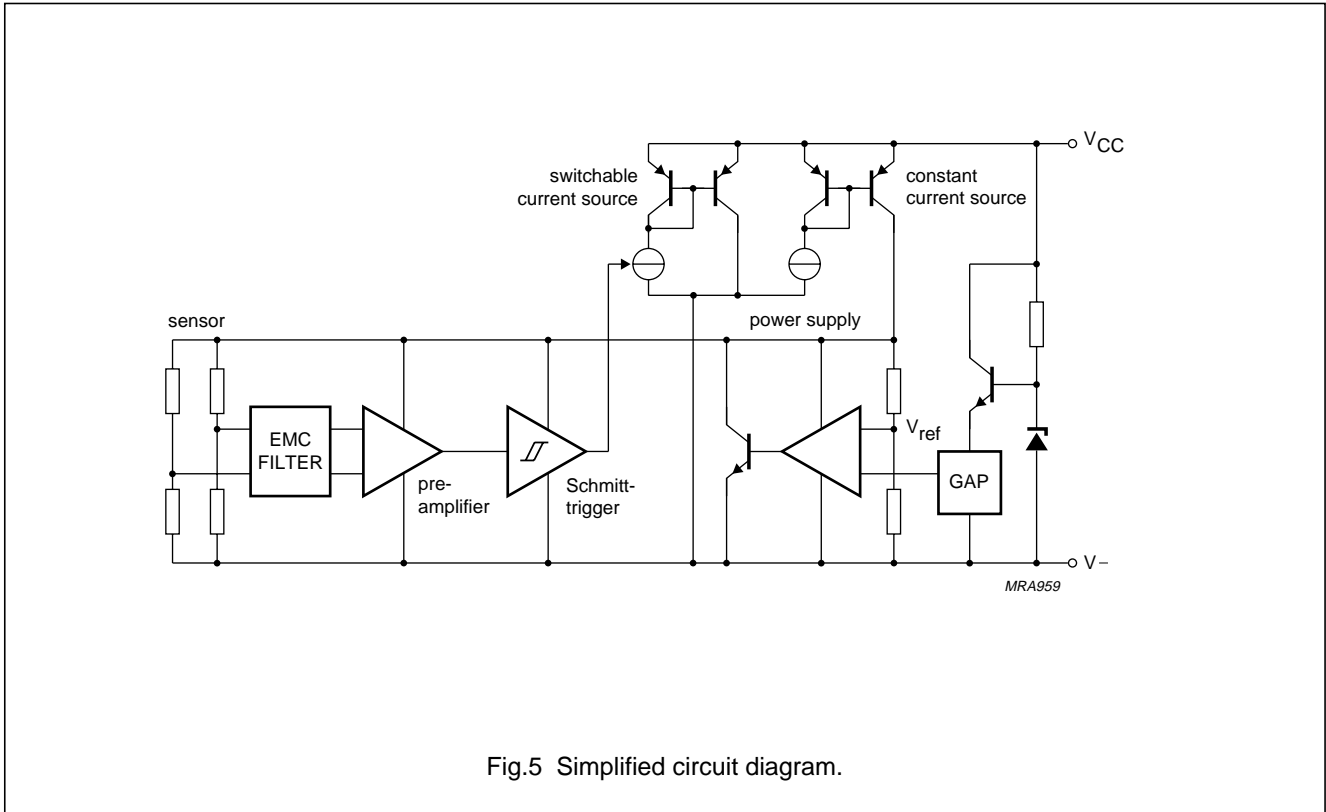


Fig.4 Block diagram.

Integrated rotational speed sensor

KMI15/2



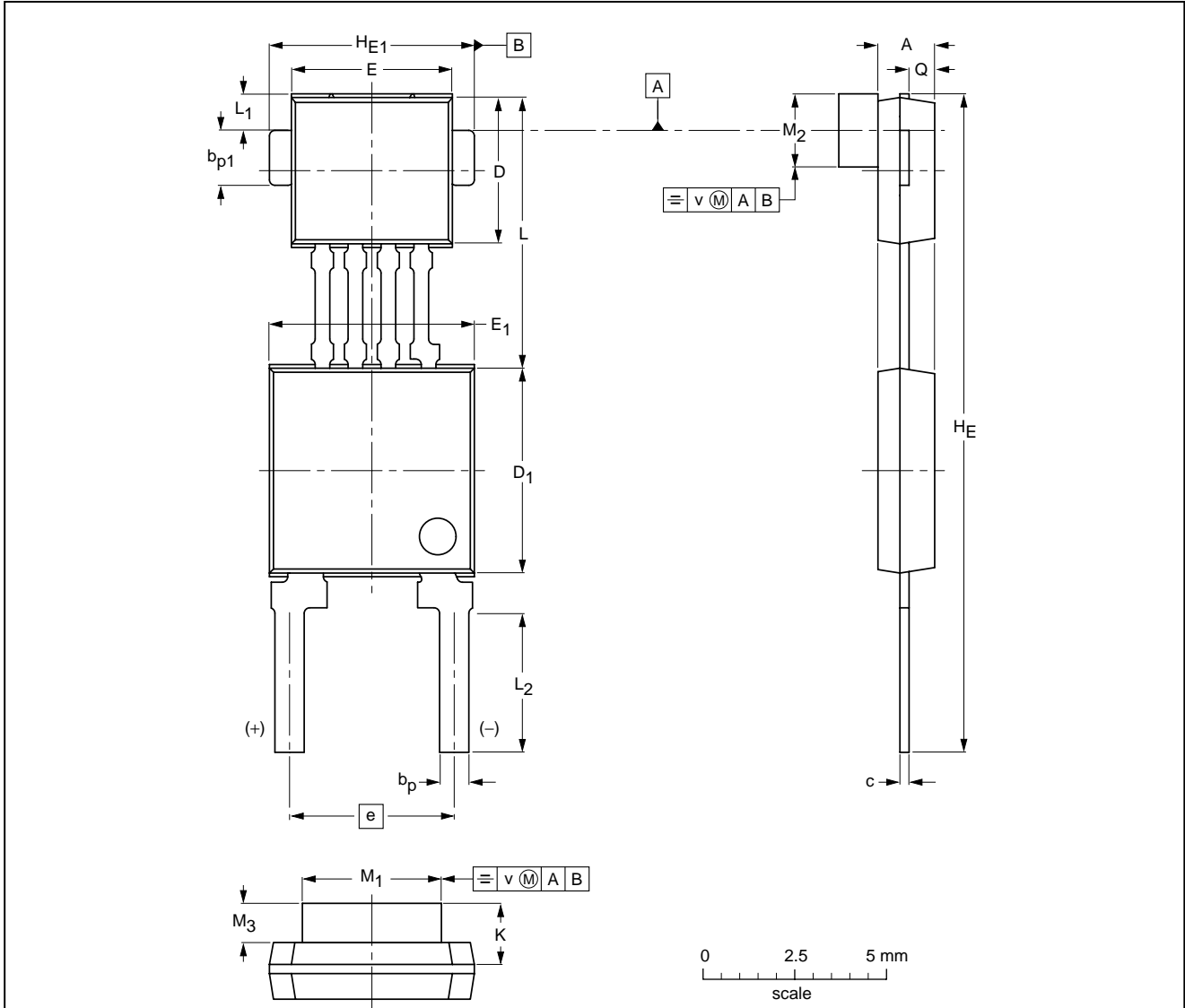
Integrated rotational speed sensor

KMI15/2

PACKAGE OUTLINE

Plastic single-ended combined package; magnetoresistive sensor element; bipolar IC; magnetized ferrite magnet (3.8 x 2.0 x 0.8 mm); 2 in-line leads

SOT453A



DIMENSIONS (mm are the original dimensions)

| UNIT | A          | b <sub>p</sub> | b <sub>p1</sub> | c           | D <sup>(1)</sup> | D <sub>1</sub> <sup>(1)</sup> | E <sup>(1)</sup> | E <sub>1</sub> <sup>(1)</sup> | e          | H <sub>E</sub> | H <sub>E1</sub> | K <sub>max.</sub> | L            | L <sub>1</sub> | L <sub>2</sub> | M <sub>1</sub> | M <sub>2</sub> | M <sub>3</sub> | Q            | v    |
|------|------------|----------------|-----------------|-------------|------------------|-------------------------------|------------------|-------------------------------|------------|----------------|-----------------|-------------------|--------------|----------------|----------------|----------------|----------------|----------------|--------------|------|
| mm   | 1.7<br>1.4 | 0.8<br>0.7     | 1.5<br>1.4      | 0.3<br>0.24 | 4.1<br>3.9       | 5.7<br>5.5                    | 4.5<br>4.3       | 5.7<br>5.5                    | 4.6<br>4.4 | 18.2<br>17.8   | 5.6<br>5.5      | 1.67              | 7.55<br>7.25 | 1.2<br>0.9     | 3.9<br>3.5     | 3.9<br>3.7     | 2.1<br>1.9     | 0.9<br>0.75    | 0.75<br>0.65 | 0.25 |

Note

1. Plastic or metal protrusions of 0.15 mm maximum per side are not included.

| OUTLINE VERSION | REFERENCES |       |      |  | EUROPEAN PROJECTION | ISSUE DATE            |
|-----------------|------------|-------|------|--|---------------------|-----------------------|
|                 | IEC        | JEDEC | EIAJ |  |                     |                       |
| SOT453A         |            |       |      |  |                     | 96-11-12-<br>97-02-28 |

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**Integrated rotational speed sensor****KMI15/2**

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**DEFINITIONS**

|   |   |
|---|---|
| <b>Data sheet status</b>  |   |
| Objective specification   | This data sheet contains target or goal specifications for product development.       |
| Preliminary specification   | This data sheet contains preliminary data; supplementary data may be published later. |
| Product specification   | This data sheet contains final product specifications.                                |
| <b>Limiting values</b>  |   |
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| <b>Application information</b>  |   |
| Where application information is given, it is advisory and does not form part of the specification.   |   |

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NOTES

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**NOTES**

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**NOTES**

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